DIY Communicator & Thermal Cam **Build Instructions** 

ChatterBox firmware allows you to communicate securely off-grid. It runs on Lilygo T-Deck and looks similar to a texting app.

Instead of internet & cell service, it uses LoRa, meshing, encryption, and digital signatures for local communication and does not require service or infrastructure and works during a grid outage.





# **ChatterBox Firmware**



After assembling this device, download the firmware for free from chatters.io. Although certain features of ChatterBox require a license fee, use of the thermal camera does not.



#### User Guide

How to use the T-Deck with ChatterBox



#### **How it Works**

How messaging works in ChatterBox



## **Firmware**

T-Deck firmware flash page



# **Fully Compatible with ChatterBox Clusters**

If you have (or build) your own private ChatterBox comms cluster, this thermal communicator will be fully compatible! Learn more at: https://chatters.io



#### Notice: Assemble at Your Own Risk

You should be familiar with electronics and soldering before attempting this project. This document may contain mistakes. Often there is variation in components, such as polarity being reversed, so you need to understand this thoroughly. *Mistakes or faulty/incorrect* hardware could result in injury, fire, or other damage.



# **DIY Thermal Cam + Communicator**

Components Needed:



Lilygo T-Deck
Download/Print a 3D Case

**Micro SD Card**See site for compatible options

**Thermal Cam:** Adafruit MLX9064 (50° Fov)

# Sources we used for this build:

#### **Soldering Tools**

You will need some basic soldering supplies for connecting wires to one another and to the T-Deck. Heat shrink wrap is also recommended.

## **Other Supplies**

There may be other miscellaneous supplies/tools not mentioned here.

TDeck	Rokland, Amazon	Dev board (not complete)
Battery	<u>Amazon</u>	3.7 LiPo, 5000 mAh
Thermal Cam	<u>Adafruit</u>	MLX 90640
Realtime Clock	<u>Adafruit</u>	DS3231 (Stemma QT)
GNSS/GPS	DFRobot 1103, DFRobot TEL0157	Either option works, often available at Digikey
Antenna	<u>Amazon</u>	Antenna + pigtail
Micro SD Card	<u>Amazon</u>	Check <u>compatablity list</u>
Wires	<u>Qwiic,</u> <u>Battery Connector</u> <u>Grove Stemma to Qwiic</u>	Check your battery polarity to get correct connector!
Nuts/Bolts	M3 Heat Inset Nuts, M3 Screws, Laptop Screws	You may use other options, these are what we use



#### **Print Your Case**

<u>Download printable enclosure</u> files (includes 3MF and STL formats).

I use Black ABS for the front and colored PLA for everything else.



#### **Connect Thermal Cam**

Join the Grove Connector to a Qwiic connector as shown, or if you've got the Grove: Qwiic adapter from the parts list, just use that.

Yellow/Clk → Grove Yellow → T-Deck RX
Blue/Data → Grove White → T-Deck TX
Red → Red → T-Deck VCC
Black → Black → T-Deck GND



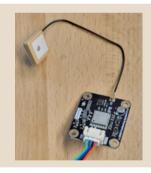


## Create a DFRobot / Qwiic Adapter

Create an adapter wire that will allow the DFR cables to attach directly to any Stemma/Qwiic plug. I heat-shrink wrap the connections (they must be insulated). This one there is no pre-made adapter I could find, because the ground/vcc seem to be reversed.

Qwiic Yellow/Clk → DFR Blue/Clk Qwiic Blue/Data → DFR Green/Data Qwiic Red → DFR Red Owiic Black → DFR Black





# Prepare the DFRobot GNSS

Move the DFR's switch to *IIC*, and then use a wire cutter/clipper to clip the long plastic switch much shorter. It will just be in the way later on if you don't.

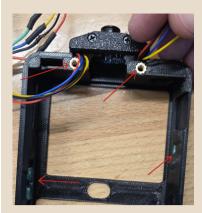
Also, attach the GPS antenna, as well as the cable you just made.





# **Connect all Components**

Connect all components together in the order shown.



#### **Add Enclosure Nuts & Switch Covers**

Insert the power switch cover and reset button cover into the T-Deck enclosure. You may need to trim the button areas of the enclosure slightly so the switches slide easily.



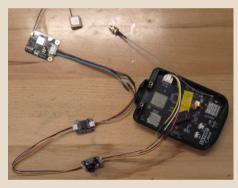
Insert the two heat-sink nuts into the enclosure. A special soldering tip makes this extremely easy, but you can also use a heat gun and apply pressure with a phillips screwdriver.

Finally, add the thermal cam (upside down as shown) and attach the cover tiny laptop screws.



## Clip the T-Deck's Reset Button

The T-Deck's reset button is too long for the enclosure. If you don't clip it to be flush with the side of the T-Deck, the case will hold the reset button down, and the T-Deck will appear to be dead.



## **Connect Components & T-Deck**

Plug the Grove Connector into the T-Deck.

Remove the T-Deck Screen Protector.

Insulate metal surfaces of the GNSS and RTC, using electrical tape. Insulate the metal surface of the GNSS, as it could short the thermal camera when inserted.

Finally - Insert the T-Deck as shown. This is tricky, you'll have to align the USBC port of the T-Deck to the enclosure, and then carefully wedge the top of T-Deck into place. You'll have to slightly pry apart the edges and top of the enclosure to make room, while not applying too much pressure to the T-Deck screen...all while making sure the enclosure button covers don't fall out.



## Insert GPS Antenna, LoRa SMA, & Components

Insert the GNSS antenna into the top of the case.

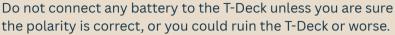
Push the LoRa SMA connector through the case opening and use a nut to keep it securely in place.

Arrange all the other components/wires as shown, so the battery will fit.



## Add the Battery and Attach the Cover

Pay special attention to battery polarity vs T-Deck polarity! For my particular battery and T-Deck, the adapter shown on the right matches up perfectly, as it switches the T-Deck's polarity to match the battery. Yours may be different!







## Add the Battery, Attach the Cover & Antenna

Attach the enclosure's back using a couple of M3 screws.

Insert a compatible SD card.

Now you are ready to flash the firmware.

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DOWNLOAD 🔱



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#### **Firmware Download Mirrors**

https://chatters.io/firmware

https://www.offgridcomms.club/firmware/esp32/

https://www.meshcomms.club/firmware/esp32/

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